



Modeling Structural - Dynamics Systems in MODELICA/Dymola, MODELICA/Mosilab and AnyLogic

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Working task



Given:

The problem definition of the constrained pendulum like in ARGESIM Comparison 7.

Wanted:

Capable simulation environment with an easy to use, object oriented interface.



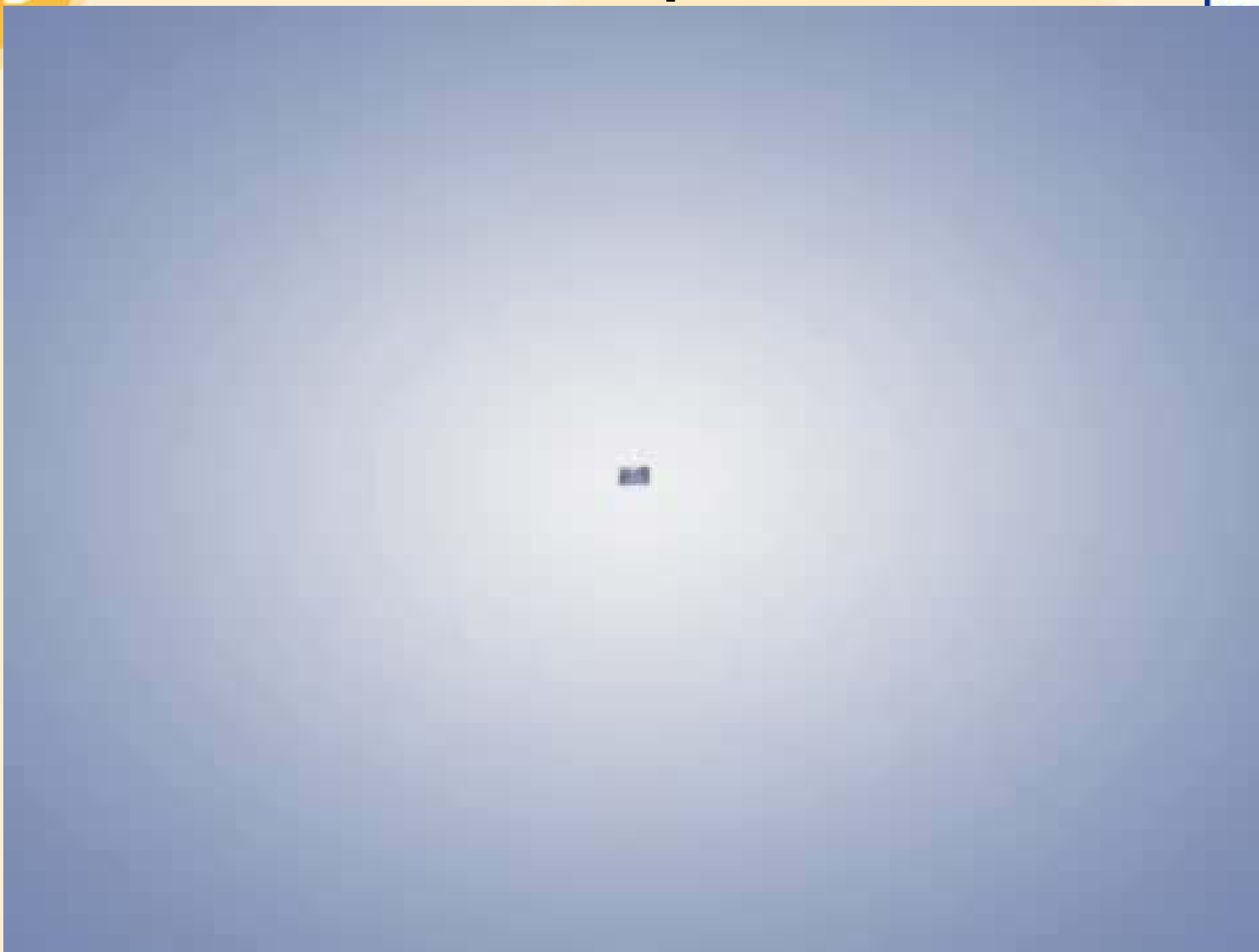
Problem definition



- What is standard in advanced modeling and simulation?
- Where are the problems?
- How to deal with them?
- Is there a standard test example?



Constrained pendulum





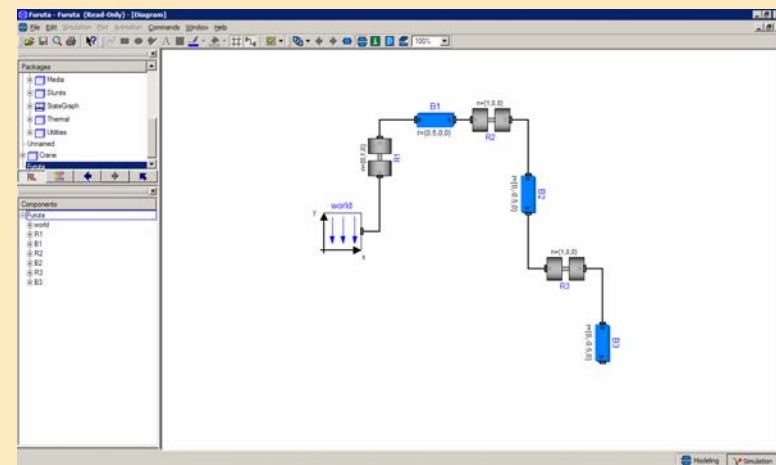
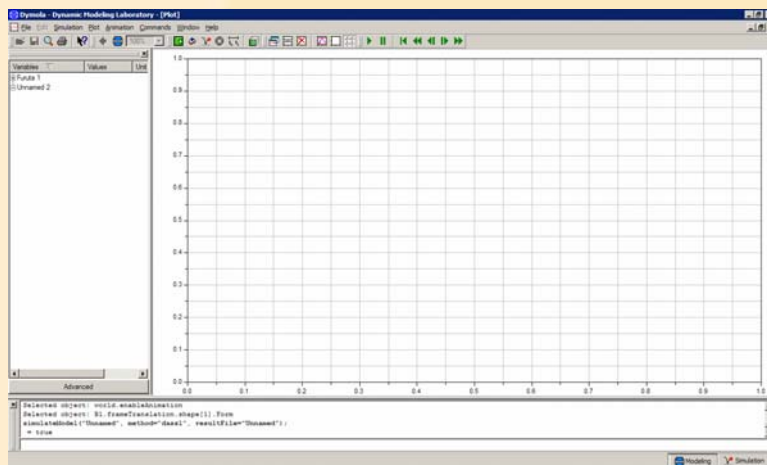
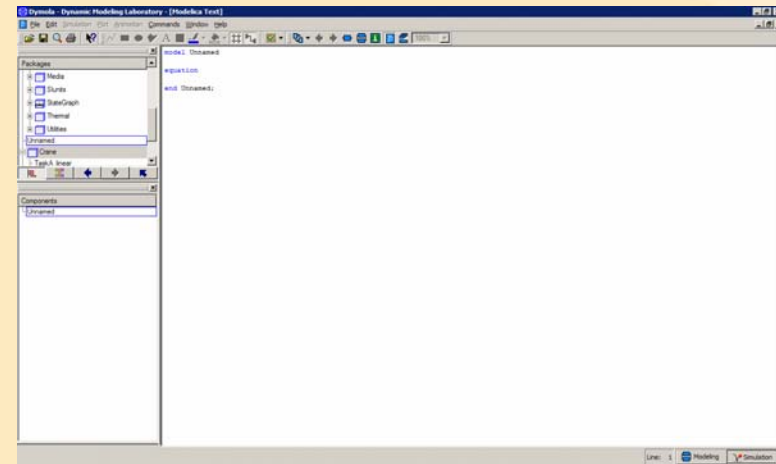
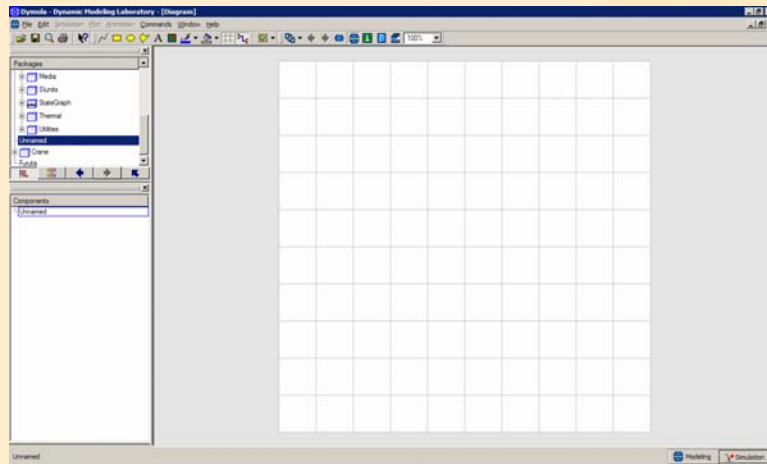
Basic formulars



$$\dot{\varphi} = \frac{v}{l}, \quad \dot{v} = -g \sin \varphi - \frac{d}{m} v$$

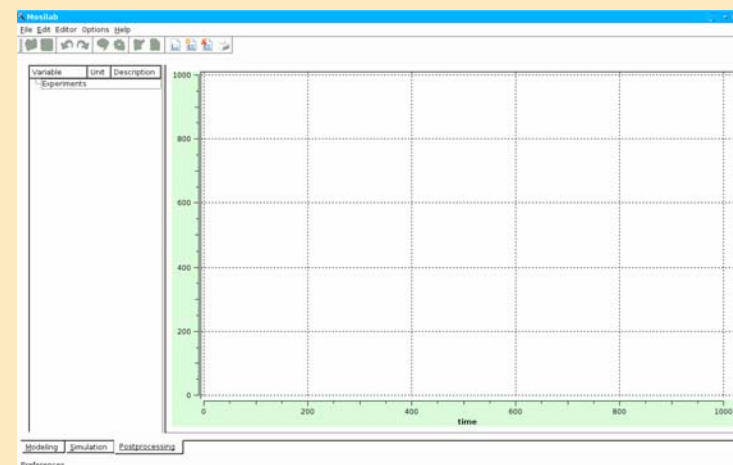
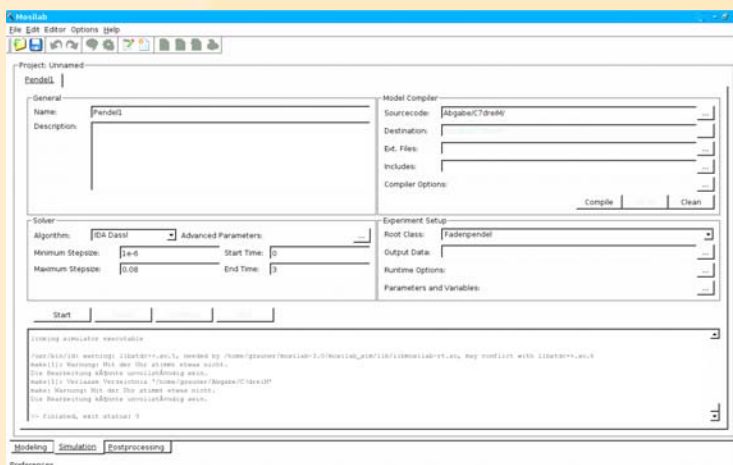
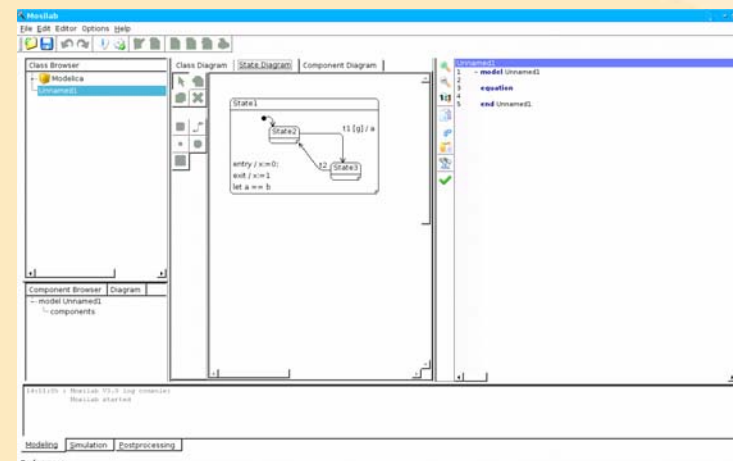
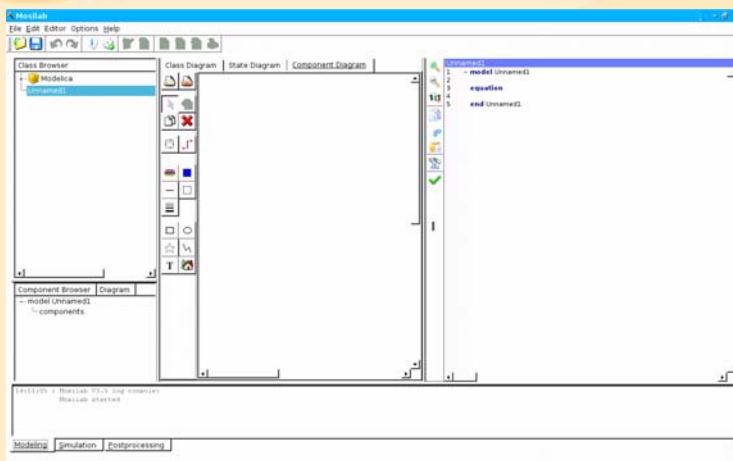


Simulator - Dymola



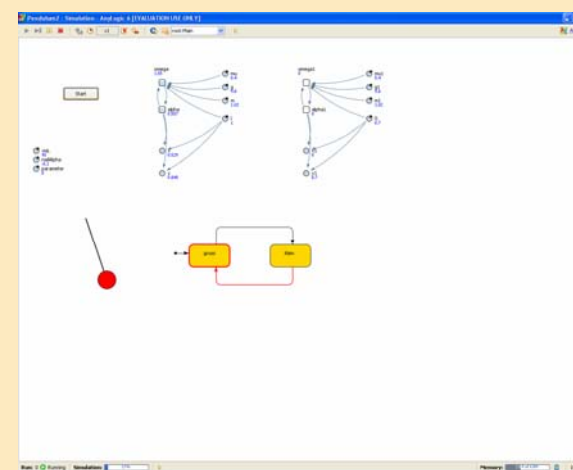
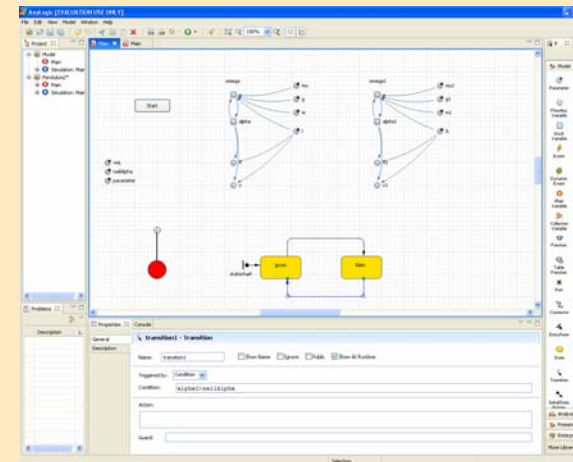
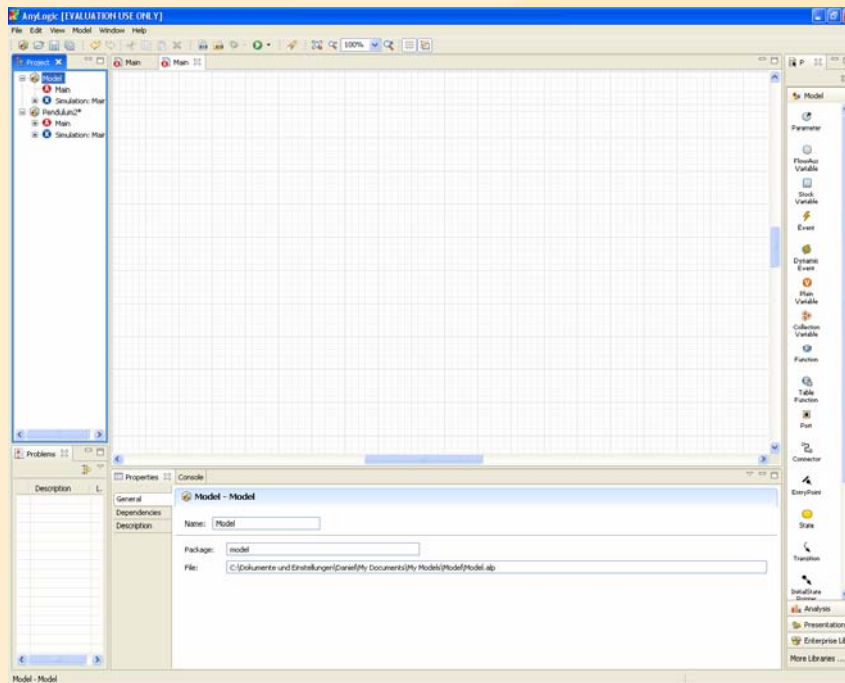


Simulator - Mosilab





Simulator - AnyLogic





Solution methods



- Algorithm section
- Parameter state event
- Model switching
 - two instances of one model
 - two separate submodel definitions



Algorithm section



Benefits:

- Modelica standard notation (Dymola, Mosilab, OpenModelica, ...)
- Fast modeling

Disadvantages:

- No graphical interface
- Limited applicability



Parameter state event



Simple equation start in
the .. here /*pendulum*/ -equations

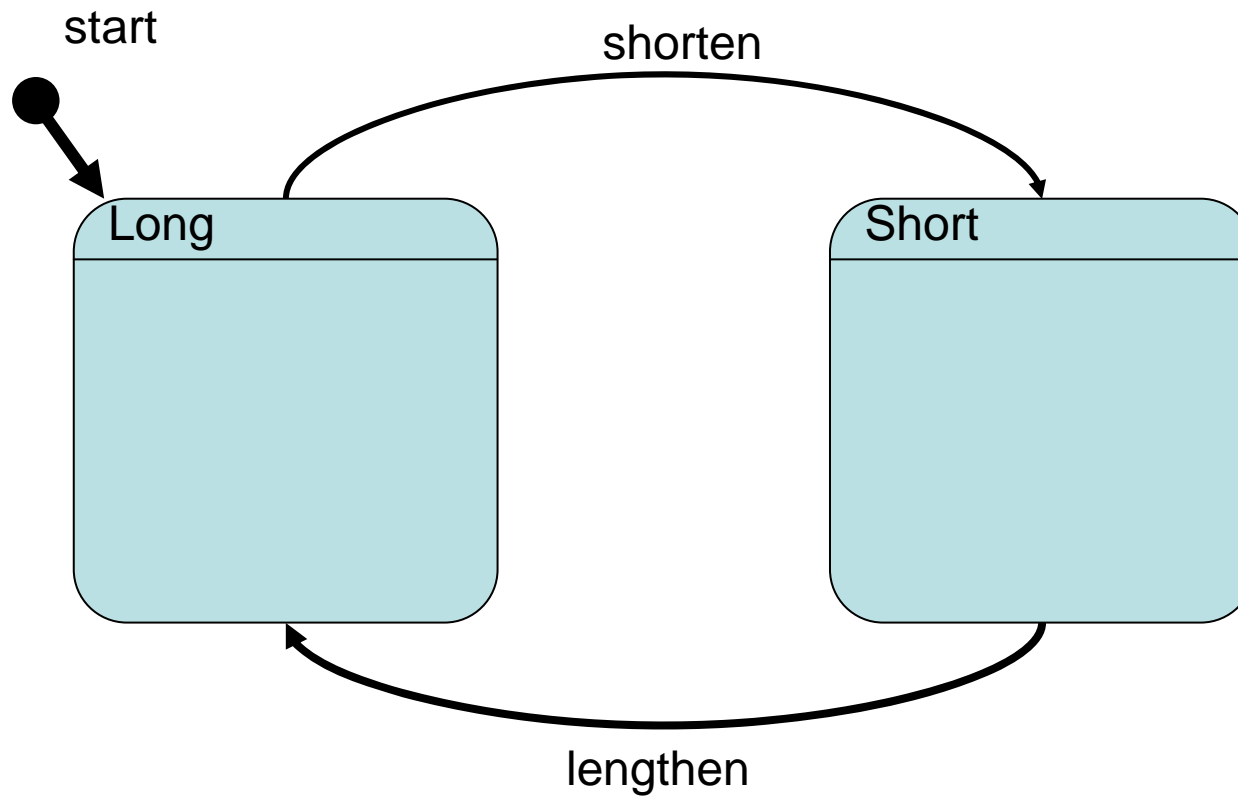
- Test
 - Only
 - Graphics
- ```
statechart
state LengthSwitch extends State;
 State Short, Long, Initial(isInitial=true);
transition Initial -> Long end transition;
transition Long->Shortevent shorten action
 length := ls;
end transition;
transition Short->Longevent lengthen action
 length := ll;
end transition;
end LengthSwitch;
```



# Model switching



## Constrained Pendulum

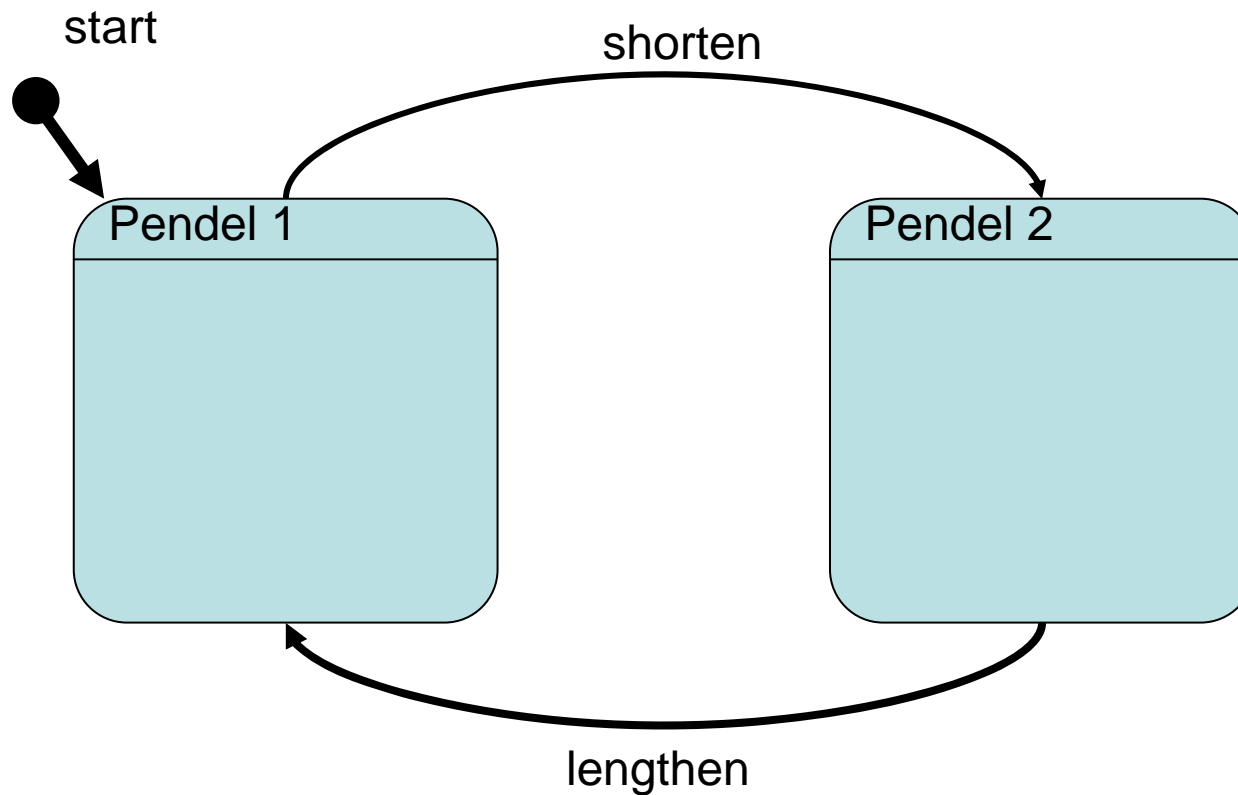




# Model switching

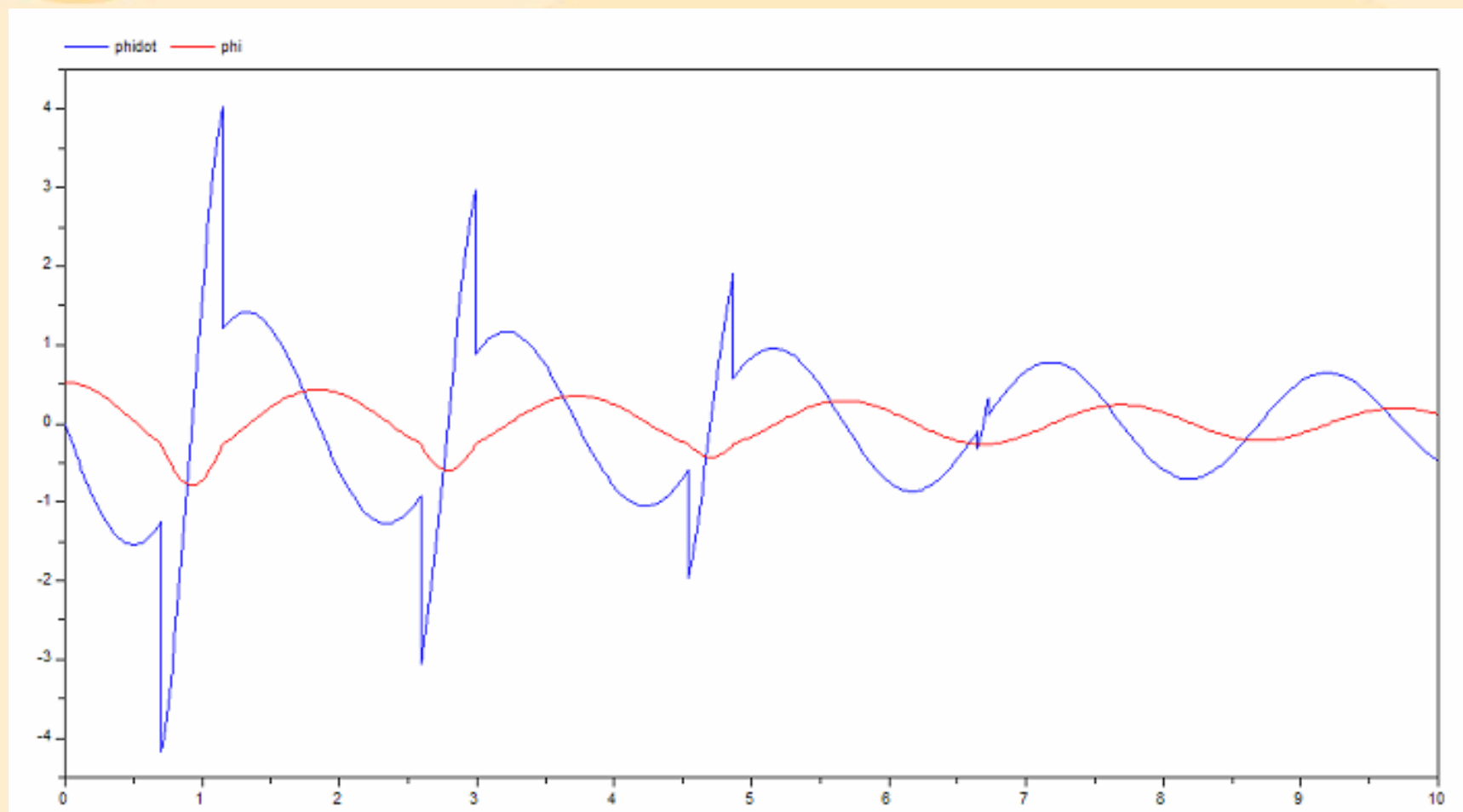


## Constrained Pendulum





# Results





# Results



| <b>Simulator</b>                           | <b>Time point</b> | <b>Method</b>                                    |
|--------------------------------------------|-------------------|--------------------------------------------------|
| Dymola/Modelica                            | 6.72198           | Dassl<br>500 intervals                           |
| Mosilab/Modelica<br>Switch models          | 6.7204            | IDA Dassl<br>Min. step 1e-6<br>Max. step 0.08    |
| Mosilab/Modelica<br>Pure Modelica          | 6.7199            | Impl. Trapez<br>Min. step 1e-6<br>Max. step 1e-4 |
| Mosilab/Modelica<br>Parameter<br>switching | 6.7224            | IDA Dassl<br>Min. step 1e-6<br>Max. step 0.08    |
| AnyLogic                                   | 6.725             | No influence<br>Step size 0.001                  |



# Conclusion



- What is standard in advanced modeling and simulation?
  - Modelica standard for model exchange
  - UML
  - combination of both
- Problems in solution generation:
  - limited state event handling (Dymola)
  - restriction in the choose of simulation methods (Mosilab)
  - no state event finding, fixed solution method (AnyLogic)





**THANK YOU  
FOR YOUR  
ATTENTION!**